

# Worthiness Based Social Scaling

Giulio D'Epifanio

## Abstract

The construction of a set of scales is delineated, for evaluating the performance of social agents (e.g. providers of services as hospitals, schools, etc.) conditionally on “reference states”  $x := X \in \{x_1, \dots, x_R\}$  of the governed individuals. Each scale is associated to an index which uses conditional “worthiness increases”  $\omega_{l|x}$ , between the levels of an ordinal outcome indicator  $Y := l \in (0, 1, \dots, L)$ . This indicator was been defined on a scheduled, by the policy-maker (PM), chain of hierarchically ordered goals. The “worthiness increases” are interpreted by modeling interrelated latent evolutionary processes, on the scheduled goal chain, up to hyperparameters  $\gamma$  which are driven by conditions  $x$ . Then, to standardize the set of scales on a given “reference behavior”, a pseudo-Bayesian (see [1]) method is used which elicits value  $\gamma^*$  by minimizing “residual from updating” (see [4]). It norms the model specifications on the “reference data” of the (chosen a priori) “standard agent”. Finally, adhering to general requirements in rational choices from the decision theory, a standardized worthiness-based index can be implemented, which takes into input the agents actual data.

**Key words:** performance index, ordinal scaling, worthiness

## 1 Indexing worthiness

The performance of any social agent  $u$  is associated to the “social behavior”, described by the set of distributions (e.g. see table 1)  $p_{|x}[u] := (p_{0|x}, p_{1|x}, \dots, p_{L|x})[u]$ , which were realized on the set of the individuals that  $u$  governs, upon the levels of

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G. D'Epifanio  
Depart. of Political Sciences, via A. Pascoli 06123 Perugia Italy, e-mail: ggiuliodd@gmail.com.it

an ordinal classifier of outcome  $Y$  varying the status  $x := X \in \{x_1, \dots, x_R\}$  of the governed individuals.

agent A1	performance level (Y)					agent A2	performance level(Y)					agent A3	performance level(Y)					agent A4	performance level (Y)				
status (X)	I	II	III	IV	V	status (X)	I	II	III	IV	V	status (X)	I	II	III	IV	V	status (X)	I	II	III	IV	V
x1	0	0	0	0	0	x1	2	2	0	0	0	x1	0	3	1	0	0	x1	1	3	0	0	0
x2	2	9	5	0	0	x2	3	13	9	1	0	x2	2	24	16	0	0	x2	16	37	18	0	0
x3	0	3	18	0	0	x3	1	20	31	4	1	x3	0	20	48	1	0	x3	0	36	59	4	1
x4	0	3	17	3	0	x4	1	3	59	8	1	x4	0	2	53	3	0	x4	0	12	107	10	0
x5	0	0	14	9	4	x5	0	6	48	18	3	x5	0	0	49	30	2	x5	0	0	87	43	4

**Table 1** Example. Actual data of the social agents to be evaluated

reference agent A0	performance level (Y)				
status (X)	I	II	III	V	V
x1	3	8	1	0	0
x2	23	83	48	1	0
x3	1	79	156	9	2
x4	1	20	236	24	1
x5	0	6	198	100	13

**Table 2** Example. Reference data of the standard-agent  $A_0$

Suppose that the PM has specified a certain chain of, increasingly challenging, binary-outcome goals

$$O_0 \preceq O_1 \preceq O_2 \preceq \dots \preceq O_l \preceq \dots \preceq \dots \preceq O_{L-1} \preceq O_L := O_{Full}, \quad (1)$$

which are hierarchically (i.e. Guttman like) ordered. Then, the (nominally recoded on  $\{0, 1, \dots, L\}$ ) ordinal outcome indicator  $Y$  is defined so that the event occurrence " $Y \geq l$ " identifies the achieving of the  $l$ -th scheduled goal  $O_l := (Y \geq l)$ ,  $l := 0, \dots, L$ . Therefore, the pursued "full purpose" could be realized at different degree of achieving, from the "tautological" (i.e. always achieved) goal  $O_0 := (Y \geq 0)$  toward the final goal  $O_L$ . Let  $\mathcal{P}^*$  denote the population of the (real or perhaps virtual) individuals which are governed by the reference agent (e.g. a recognized "best practice" for standardization)  $A_0$  (e.g. see table 2). Then, the criterion of intrinsic worthiness (see [3]) may be interpreted<sup>1</sup> on a goal-based probabilistic setup as follows.

*For any actual individual  $i$ , having achieved goal  $O_{l-1}$  on chain of goals (1), the higher "the risk of failing the next goal  $O_l$ ", referring such a risk on the population  $\mathcal{P}^*$ , the greater the "increase of worthiness", due to the performance of the agent which governs  $i$  "as if"  $i$  was in  $\mathcal{P}^*$ , whenever it actually achieves goal  $O_l$ .*

<sup>1</sup> Consider hierarchical chain of goals (1). Given that a certain goal  $O_{l-1}$  has been achieved, the greater the resistance, with reference to the evaluation framework, to also achieve the next pursued goal  $O_l$ , by continuing to improve, the greater the increment of value due to the intrinsic worthiness of who, effectively, is able to achieve it.

Thus, the  $\mathcal{P}^*$ -standardized, conditionally on status  $x := X \in \{x_1, \dots, x_R\}$ , worthiness increase between any two adjacent levels of  $Y := l \in (0, 1, \dots, L)$  is provided<sup>2</sup> (for  $l := 1, \dots, L$ ) by:

$$\begin{aligned} \omega_{l|x}^* &:= \Delta_{l-1} \text{Val}_{|x} := \text{Val}_{|x}(O_l) - \text{Val}_{|x}(O_{l-1}) = \\ &= \varphi_l \left( \frac{\text{Pr}\{Y = l-1|x; \mathcal{P}^*\}}{\text{Pr}\{Y \geq l-1|x; \mathcal{P}^*\}} \right) = \varphi_l \left( \frac{p_{l-1|x}}{p_{l-1|x} + p_{l|x} + \dots + p_{L|x}} \right) \geq 0 \end{aligned} \quad (2)$$

Here, continuous monotone functions  $\varphi_l(\cdot)$  (e.g. set here the identity) of the conditional probability rates may be chosen (see [3]) for specifying some characteristics (e.g. the additivity) of the scale. Formally re-interpreting “worthiness increases” as “utility increases”, functionals of the “rank dependent expected utility”, adhering to requirements of rational choices (e.g. see [2], pp. 559), leads to the following instance of conditional-expectation-based index<sup>3</sup>:

$$u \mapsto W[p_x[u]; \omega_x^*, x] := \sum_{l=1}^L \varphi_l \left( \frac{\text{Pr}\{Y = l-1|x; \mathcal{P}^*\}}{\text{Pr}\{Y \geq l-1|x; \mathcal{P}^*\}} \right) \cdot (1 - F_{Y|x}[p][u])(l) \quad (3)$$

Here,  $F_{Y|x}[p]$  denotes the cumulative distribution such that  $F_{Y|x}[p](l) = p_{0|x} + p_{1|x} + \dots + p_{(l-1)|x}$ . Thus, through  $x \in \{x_1, \dots, x_R\}$ , it may be defined the global evaluation index:  $u \mapsto \sum_{r=1}^R q_r \cdot W[p_{x_r}([u]; \omega_{x_r}(\mathcal{P}^*))]$ . It uses the actual agents data (e.g. see table 1)), standardized on the reference-agent’s data (e.g. see table 2). Here,  $q_r \geq 0$  ( $\sum_{i=1}^R q_r = 1$ ) weights<sup>4</sup> the reference domain for the status  $x_r$ .

## 2 Eliciting standardized worthiness increases

To justify differences in “worthiness increases” (2), through reference conditions  $x := X \in \{x_1, \dots, x_R\}$ , the PM may adopt some “reference evaluation criterion” and working assumptions formally specified by means of a structural probabilistic model (4)-(7). Here<sup>5</sup>, the conditional rates  $(1-v_{rl})$  (which enter “worthiness increases”

<sup>2</sup> It is the worthiness credit which is gained by any social agent in improving the condition of a “standard individual”, in the reference condition  $x \in \{x_1, \dots, x_R\}$ , from the current level  $(l-1)$  to the next  $l$  on the scale of  $Y$  which was constructed on goal chain (1).

<sup>3</sup> for any agent  $u$ , given  $x$ , it takes into input the distribution realized (e.g. see table 1), by the individuals that  $u$  governs in condition  $x$ , on the standardized worthiness-quantified levels of  $Y$ .

<sup>4</sup> these weights should represent the political relevancy of the “social reference domains” to the main aim of the PM.

<sup>5</sup> On the stratum of the  $n_r$  individuals in the condition  $x_r$ , the manifest outcome  $(Y_{r0}, \dots, Y_{rL})$  is distributed as a multinomial (eq.4) where the expectation-parameters  $\psi_r := (\psi_{r0}, \psi_{r1}, \dots, \psi_{rL})$  are normed, within the container Dirichlet model (eq. 5), on a set of constraints on the latent evolutionary processes undertaken the levels of outcome scale  $Y$  (eqs (6)-(7)).

(2)) are represented as latent parameters of interrelated evolutionary-processes behind the goals chain (1), which are driven by manifest conditions  $x$  up to hyper-parameters<sup>6</sup>  $\gamma := (\mu_0, \delta, \beta^X)$  to be regulated. Then, the methodological question arises in automatic eliciting of values  $\gamma^*$  so that “worthiness increases”  $\omega_{l|x}(\mathcal{P}^*; \gamma^*)$  enter evaluation indexes (3). To norm the model on the reference-agent’s data table (2), recalling a “minimum information principle”<sup>7</sup>, hyper-parameters  $\gamma$  may be regulated (e.g. see [5],[4]) to that value  $\gamma^*$  such that the “residual from updating”<sup>8</sup>  $\| \text{Vec} ( E(\Psi | y, x; \gamma, w) - E(\Psi | x; \gamma, w) ) \|$  is minimized subject to specifications of constraints (6)-(7).

$$Y_r := \{Y_{r0}, \dots, Y_{rL}\} | \Psi_r \stackrel{\text{ind.}}{\sim}_{r=1, \dots, R} \text{Mult}(y_{r0}, \dots, y_{rL}; \Psi_{r0}, \Psi_{r1}, \dots, \Psi_{rL}, m_r) \quad (4)$$

$$\Psi_r := (\Psi_{r0}, \Psi_{r1}, \dots, \Psi_{rL}) | m_r, a_r \stackrel{\text{ind.}}{\sim}_{r=1, \dots, R} \text{Dirichlet}(\Psi_{r0}, \dots, \Psi_{rL}; m_r, a_r) \quad (5)$$

$$m_r := (m_{r0}, m_{r1}, \dots, m_{rL}), 0 < m_{rl} := E[\Psi_{rl}] < 1, \sum_{s=0}^L m_{rs} = 1, \quad a_r := w_r, w_r > 0 \quad (6)$$

$$v_{r1} := \frac{m_{r0}}{m_{r0} + m_{r1}} = \frac{e^{\eta_{r1}}}{1 + e^{\eta_{r1}}},$$

$$v_{rl} := \frac{m_{r0} + \dots + m_{r(l-1)}}{m_{r0} + m_{r1} + \dots + m_{rl}} = \frac{e^{\eta_{rl}}}{1 + e^{\eta_{rl}}},$$

...

$$v_{rL} := \frac{m_{r0} + \dots + m_{r(L-1)}}{m_{r0} + m_{r1} + \dots + m_{rL}} = \frac{e^{\eta_{rL}}}{1 + e^{\eta_{rL}}},$$

$$\eta_{rl} = \mu_0 + \sum_{s=1}^L \delta_r \cdot I_{(s=l)} + \sum_{w=2}^R \beta_w^X \cdot I_{(X(r)=w)} \quad (7)$$

reference condition  $r=1, \dots, R:=5$ ; scale level transitions  $l:=1, \dots, L:=4$

## References

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<sup>6</sup> Hyper-parameters  $\mu_0, \delta$  represent, respectively, the common base-line and increments in the level scores of the scale; instead, the parameters of profile  $\beta^X$  represent the crossed effects of condition and levels, in transition processes. Here,  $I_{(\cdot)}$  denote a binary indicator function.

<sup>7</sup> “The less a prior representation of knowledge is updated by current data, the more intrinsically it already was accounted for by the *intrinsic information* added by such data”

<sup>8</sup> Here,  $E(\Psi | y, x; \gamma, w)$  denotes the predictive expectation of full parameter profile  $\Psi := (\Psi_1, \dots, \Psi_R)$  which is updated by outcome  $y$ , whereas  $E(\Psi | x; \gamma, w)$  is his non updated counterpart, over the design-point  $x$

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